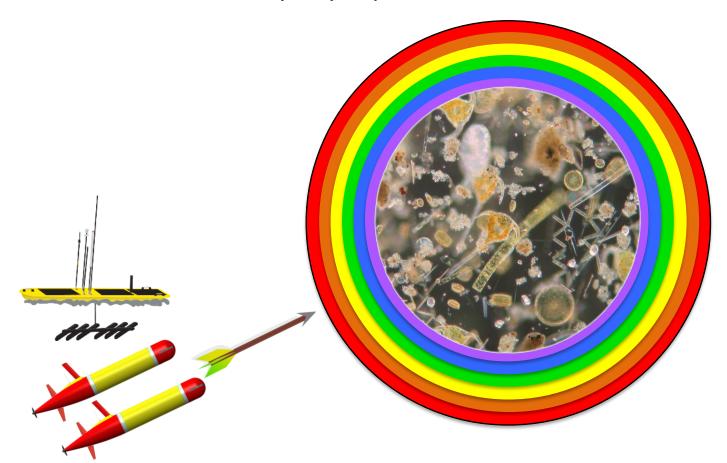
Targeted Sampling Enhanced by Multi-Vehicle Collaboration

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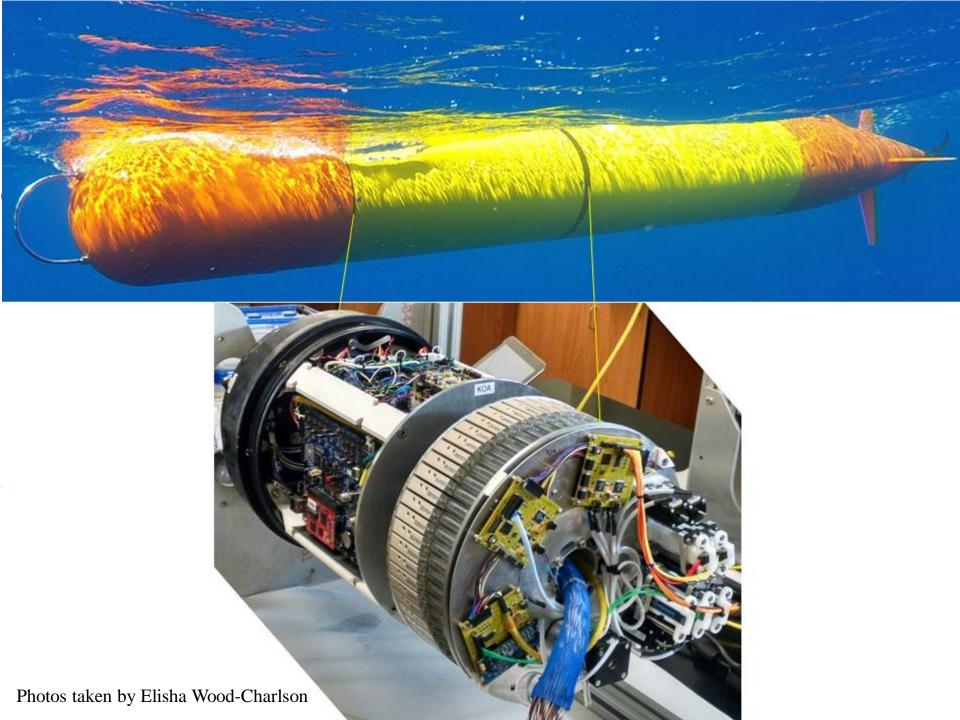




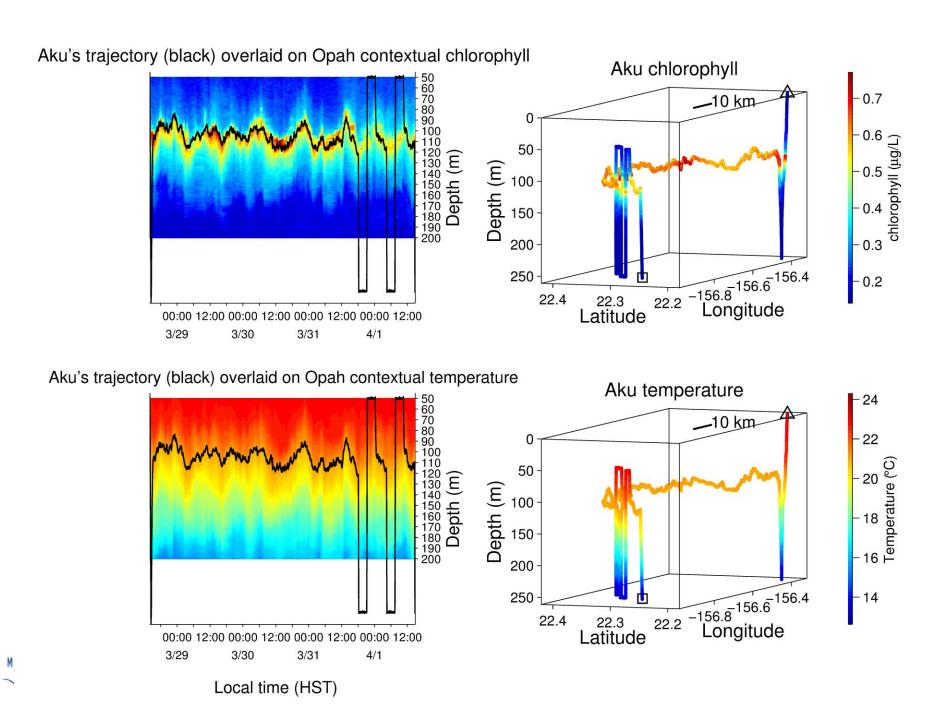
Outline

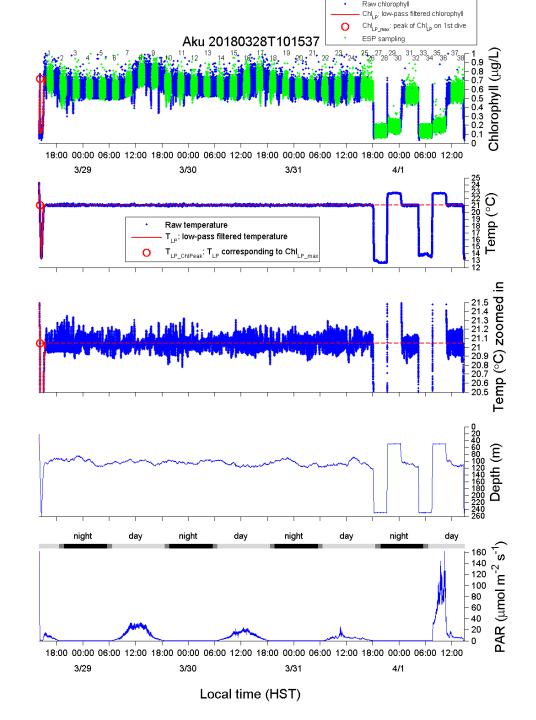
- Motivation: Multi-vehicle collaboration improves efficiency and persistence of targeted sampling of oceanographic features.
- Application example: March/April 2018 Hawaii experiment
- Ongoing and future work





Trajectories of Aku (red), Mola (white), and Opah (green) from 3/28 13:57 to 4/1 14:34 overlaid on 3/31 14:00 CMEMS SLA and surface current velocity map 23 -0.2 m/s 22.8 -50 km 22.6 --2 22.4 -- 0 22.2 ---2 Latitude SLA (cm) 22 -21.8 --6 21.6 -8 21.4 -10 21.2---12 21 --157.8 -157.6 -157.4 -157.2 -157 -156.8 -156.6 -156.4 -156.2 -158 Longitude



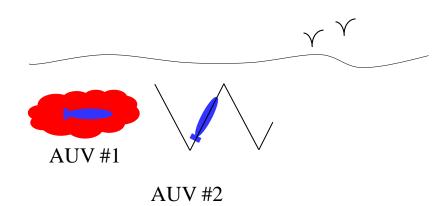




Multi-vehicle collaboration for tracking and sampling phytoplankton patches

AUV#1 drifts with a chlorophyll patch and observes it from boom to bust.

AUV#2 yo-yos in the neighborhood to search for other patches.



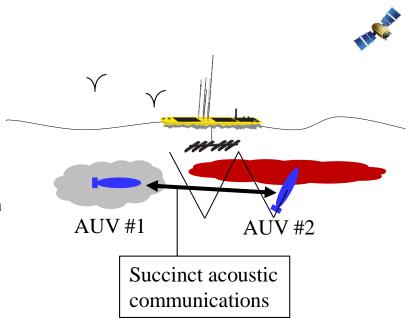
The chlorophyll patch tracked by AUV#1 fades out.

AUV#2 finds a new chlorophyll patch some distance away. AUV#2 transmits to AUV#1 the following key information via acoustic communications:

- i) chlorophyll signal level in the new patch.
- ii) latitude/longitude of the center of the new patch.

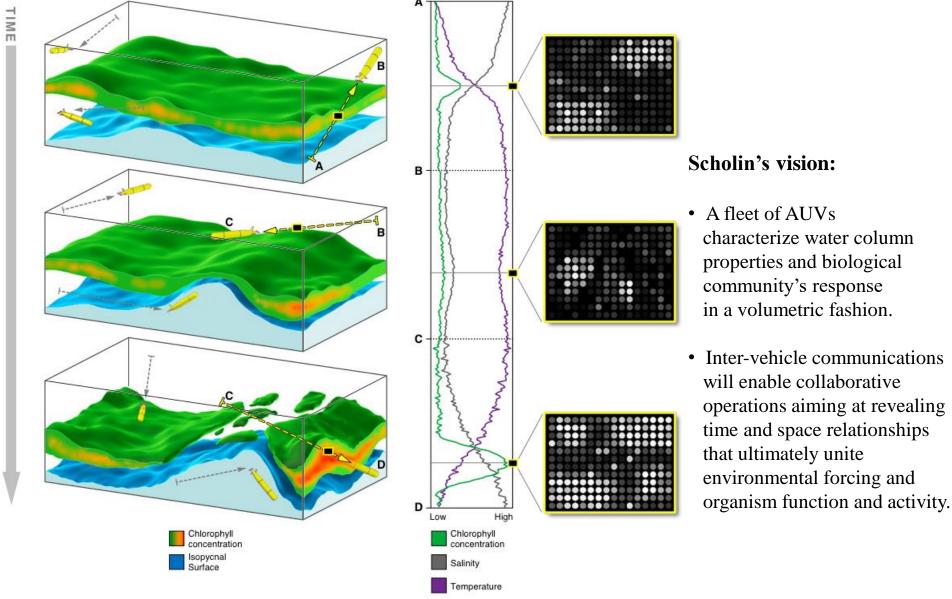
AUV#1 compares the chlorophyll signal levels of the old and new patches, and determines that the new patch is stronger and more worthy of being tracked. AUV#1 flies to the new patch center and starts to drift with the new patch and observe its variation.

Wave gliders and satellites can provide supplementary communication channels.





Multi-AUV collaborative targeted ecogenomic sensing





C. Scholin, *Ecogenomic sensors*. *In Encyclopedia of Biodiversity, Volume 2 (Levin S. A. (ed.))*, 2nd ed.

MBARI founder David Packard:

"Send instruments to sea, not people.

Return information to shore, not samples"



